HKL2000

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Data processing

X-ray data processing = changing detector output to estimate of square of structure factors amplitudes

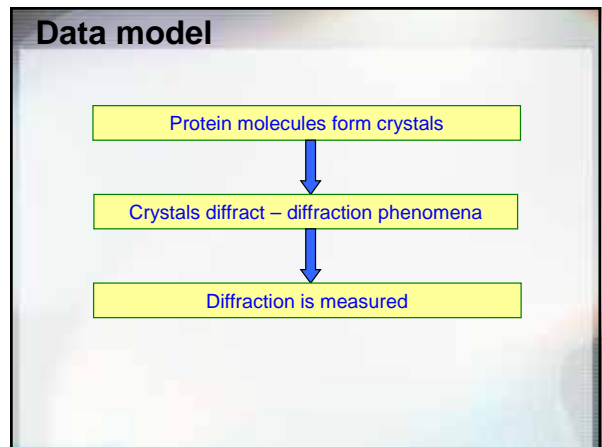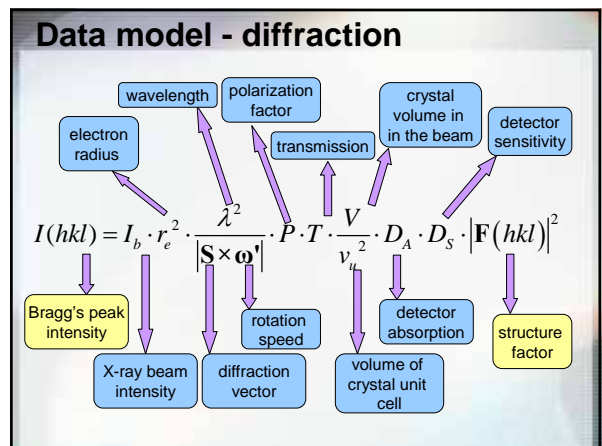$$\Rightarrow \left| \mathbf{F} \right|^2$$

Data processing in HKL2000

- Detector description (e.g. site file)
- Autoindexing (Denzo) and visual assessment (XDisplayF)
- Refinement of experimental parameters and optimization of integration parameters (Denzo)
- Integration (Denzo)
- Scaling (Scalepack)
- Merging and statistical assessment (Scalepack and HKL2000)

Data model

Protein molecules form crystals

Crystals diffract – diffraction phenomena

Diffraction is measured

Data Model of a Crystal

Crystal ≡ ideal space group symmetry in a perfectly ordered infinite crystal lattice

Deviations:
- Finite crystal size
- Ideally imperfect crystal (no double scattering and no extinction)
- Observable mosaicity
- Multiple lattices due to phase transition
- Twinning
- Pseudosymmetry
- Modulated structures (Wang, J. (2001) J. Struct. Biol. 134, 1524; Bochtler *et al.* (2001) J. Struct. Biol. 135, 281)
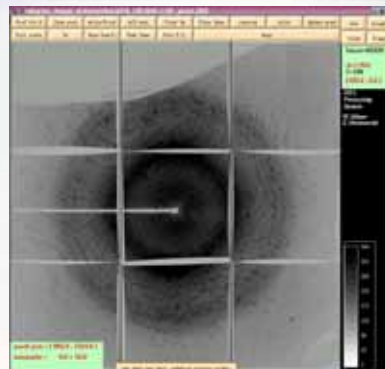

Data model - diffraction

wavelength · polarization factor · crystal volume in the beam · detector sensitivity · electron radius · transmission

$$I(hkl) = I_b \cdot r_e^{\,2} \cdot \frac{\lambda^2}{\left| \mathbf{S} \times \boldsymbol{\omega}' \right|} \cdot P \cdot T \cdot \frac{V}{v_u^{\,2}} \cdot D_A \cdot D_S \cdot \left| \mathbf{F}(hkl) \right|^2$$

Bragg's peak intensity · X-ray beam intensity · diffraction vector · rotation speed · volume of crystal unit cell · detector absorption · structure factor

Diffraction - Deviations

- Radiation damage
- Double scattering
- Uneven exposure
- Uneven rotation
- Contaminating wavelength
- Absorption

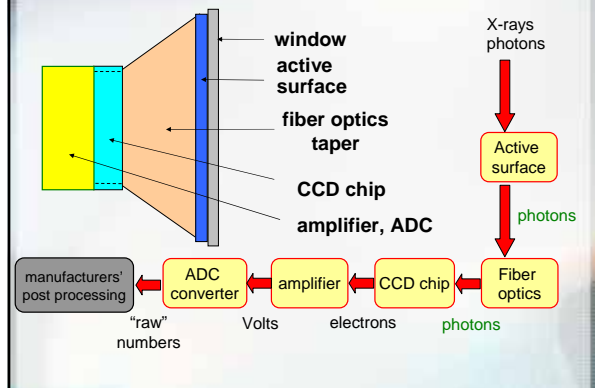## Data Model of Measurements - I

Obscuration:
1. Beam stop
2. Cryo-colling
3. Goniostat

Data Model of Measurements - II
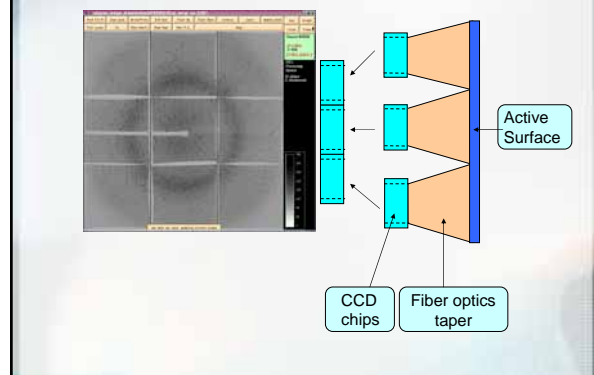

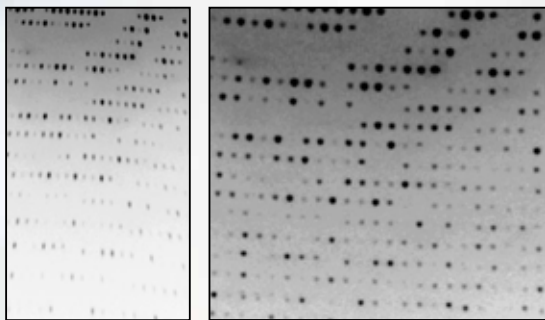## Assembly of diffraction pattern

Image distortion - magnified

Detector geometric corrections - method I

Correction of images
- allows for the use of integration software that does not apply distortion corrections
- looks nice from a distance
- closer view:
  - non-uniformly broadens spots – creates overlaps, makes profile fitting less accurate
  - flattens variations – affects error model, creates moiré pattern
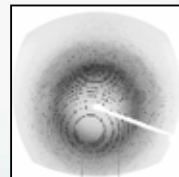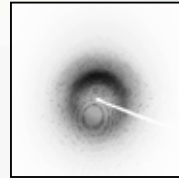- allows to simulate spherical detectors

Detector geometric corrections - method II

Correction of diffraction pattern
- requires programs to understand detector specifics
- optimizes overlaps and profile fitting
- produces a better error model
- looks a bit strange (fake gaps)

Detector description – Site file

- The site file contains numerical parameters describing how reciprocal space is distorted on diffraction image. These parameters belong to two groups: one describing geometry of distortion and optional second describing sensitivity of each pixel on the detector.

- Wrong site file results in:
- misindexation, misprediction of spots' positions, wrong refinement of processing parameters
- wrong correction of intensities due to wrong values of pixels' sensitivity

Indexing

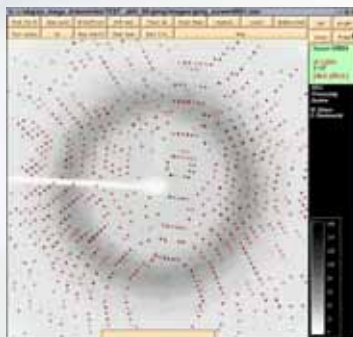Assigning hkl index to diffraction maxima (spots)

Requirements:
- approximate description of detector geometry
(x beam, y beam !!!, distance, detector orientation)
- free of artifacts list of peaks (peak search)
    * twins, ice, zingers, satellites
        - manual editing, resolution limits
- proper procedure
    * spots separation
        longest vector = distance*λ/(spot size)
    * oscillation range
        viruses   0.25⁰
        proteins   1⁰
        small molecules 2.5⁰
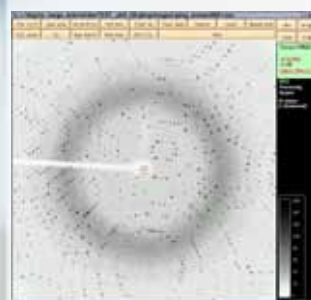
Autoindexing

- peak search
- autoindexing in primitive lattice
- choice of Bravais lattice (lattice symmetry)
- reindexing to standard symmetry
- if more than one crystal involved – checking the consistency of indexing between crystals
    - needed only for some space groups
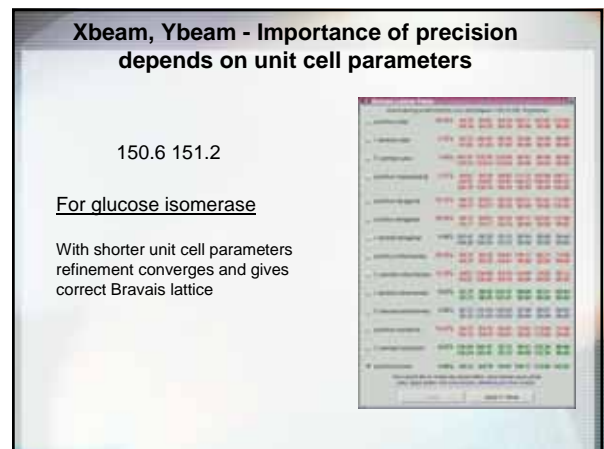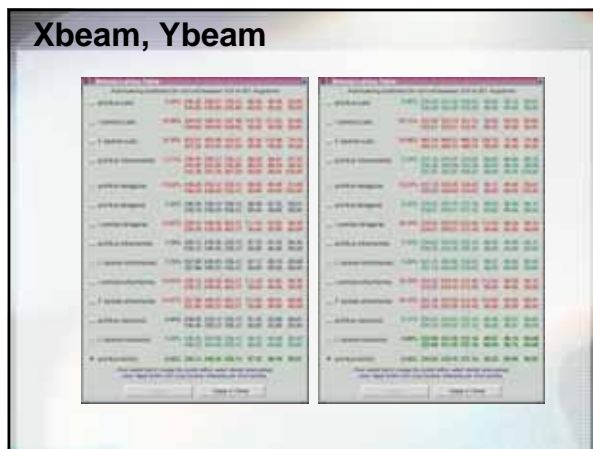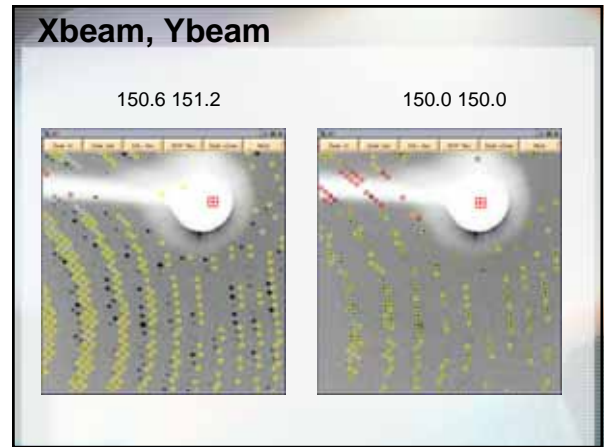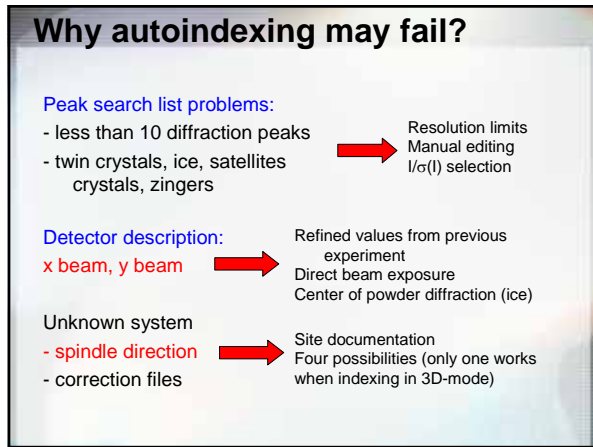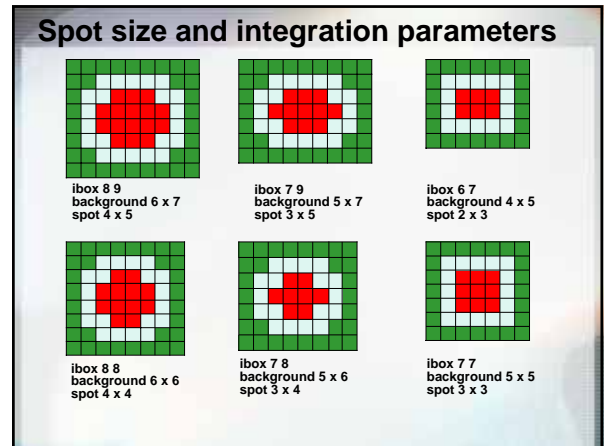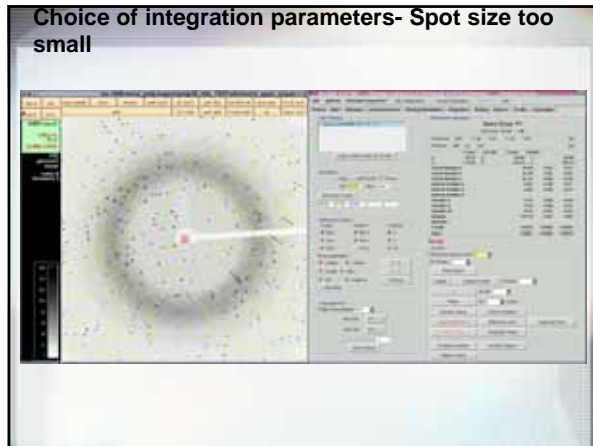   - after scaling of data from crystals separately

Peak Search

It finds the strongest intensity peaks

Autoindexing in primitive lattice and choice of higher symmetry Bravais lattice (if possible)

Choice of integration parameters- Spot size too small

Spot size and integration parameters

ibox 8 9
background 6 x 7
spot 4 x 5

ibox 7 9
background 5 x 7
spot 3 x 5

ibox 6 7
background 4 x 5
spot 2 x 3

ibox 8 8
background 6 x 6
spot 4 x 4

ibox 7 8
background 5 x 6
spot 3 x 4

ibox 7 7
background 5 x 5
spot 3 x 3

Why autoindexing may fail?

Peak search list problems:
- less than 10 diffraction peaks
- twin crystals, ice, satellites
  crystals, zingers

Resolution limits
Manual editing
I/σ(I) selection

Detector description:
x beam, y beam

Refined values from previous
  experiment
Direct beam exposure
Center of powder diffraction (ice)

Unknown system
- spindle direction
- correction files

Site documentation
Four possibilities (only one works
  when indexing in 3D-mode)

Xbeam, Ybeam

150.6 151.2   150.0 150.0

Xbeam, Ybeam

Xbeam, Ybeam - Importance of precision depends on unit cell parameters

150.6 151.2

For glucose isomerase

With shorter unit cell parameters
refinement converges and gives
correct Bravais lattice

Why autoindexing may fail?

- Procedure problems:

$$longest\ vector = \frac{distance \cdot \lambda}{spot\ size}$$

- **spot size** reduce spot radius
- **distance** re-collect image at longer distance
- **mosaicity too large** reorient the crystal if only one axis is affected
- **rotation range too large** decrease for large unit cells, but even if indexing works there may be too many overlaps

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Refinement of instrument and crystal parameters

Crystal: - orientation (rotx, roty, rotz)
           - unit cell
           - mosaicity
Beam: - focus parameters (crossfire x y xy - 0 values for beam focused on the detector)
Detector: - distance (distance)
           - orientation (rotx, roty, rotz)
           - position (x beam, y beam)
           - internal geometry (radial offset, angular offset, y scale, skew, distortions)

The parameters could be the same or different for consecutive images

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Refinement - target

Minimization of target function
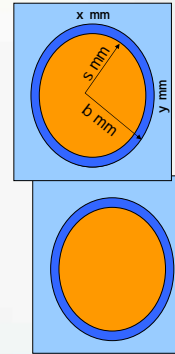
$$\chi^2_{total} = \chi^2_x + \chi^2_y + \chi^2_p$$

$$\chi^2_x = \sum_{spots} \frac{\left(x_{predicted} - x_{observed}\right)^2}{\sigma^2_x}; \quad \chi^2_y = \sum_{spots} \frac{\left(y_{predicted} - y_{observed}\right)^2}{\sigma^2_y}$$

$$\chi^2_p = \sum_{hkl} \frac{\left(p_{predicted} - p_{observed}\right)^2}{\sigma^2_p}; \quad p = \frac{I_{hkl,\ frame}}{I_{hkl,\ total}}$$

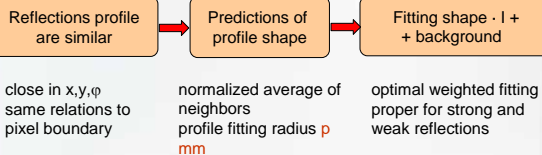The displayed values of χ^2 are divided by number of observations

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Integration of diffraction peaks - I

- based on analysis of local environment of peaks - "box" (box x_mm y_mm or ibox x_pixels y_pixels)
- definition of spot area (spot radius s_mm)
- background is outside of spot area (including other reflections) and outside of background circle (background radius b_mm)
- background is analyzed for slope (linear variations with positions) and artifacts

Spot and background are symmetric with respect to the center of the box.

Integration of diffraction peaks - II

Reflections profile are similar	→	Predictions of profile shape	→	Fitting shape · I + + background
close in x,y,φ same relations to pixel boundary		normalized average of neighbors profile fitting radius p mm		optimal weighted fitting proper for strong and weak reflections

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Scaling - definition

$$I(hkl) = I_b \cdot r_e^2 \cdot \frac{\lambda^2}{\left|\mathbf{S} \times \boldsymbol{\omega'}\right|} \cdot P \cdot T \cdot \frac{V}{v_u^2} \cdot D_A \cdot D_S \cdot \left|\mathbf{F}(hkl)\right|^2$$

scale factor K

$$K = k_{overall} \cdot \left(k_{Lorentz} \cdot k_{polarization} \cdot k_{detector} \cdot k_{absorption} \cdot ... \right)$$

From comparison of data to atomic model

From calibration and diffraction geometry

From comparison of symmetry related reflections
SCALING

Scaling - exponential modeling

$$k_s\left(observation\right) = e^{\sum_i p_i \cdot f_i\left(observation\right)}$$

optimized scale factor

unknown parameters determined by scaling

modeling functions describing various effects

Scaling - decay described by B-factor

$$f_{pb,n} = \frac{|\mathbf{S}\cdot\mathbf{S}|}{2} \cdot dose^n$$

B-factor as a continues function of accumulated dose

$$f_{b_j} = \frac{|\mathbf{S}\cdot\mathbf{S}|}{2} \quad \text{for data in batch } j$$
$$f_{b_j} = 0 \quad \text{for other data}$$

Separate B-factor for every batch

Scaling - correction for absorption

Modeling functions (spherical harmonics)

$$f_{as,lm} = \frac{1}{2}\sqrt{\frac{(2l+1)(l-m)!}{4\pi(l+m)!}}\left(P_{lm}\left(\cos\theta_i\right)\sin\left(2\pi m\Phi_i\right) + P_{lm}\left(\cos\theta_o\right)\sin\left(2\pi m\Phi_o\right)\right)$$

$$f_{ac,lm} = \frac{1}{2}\sqrt{\frac{(2l+1)(l-m)!}{4\pi(l+m)!}}\left(P_{lm}\left(\cos\theta_i\right)\cos\left(2\pi m\Phi_i\right) + P_{lm}\left(\cos\theta_o\right)\cos\left(2\pi m\Phi_o\right)\right)$$

"Pure" absorption → odd coefficients zero

odd coefficients non-zero → ? - slowly changing function

Scaling corrections – unrepresentative example

χ^2 M – merged Friedel pairs, U – unmerged Friedel pairs, AS – statistical significance of anomalous signal defined as a ratio χ^2 M to χ^2 U. When the value AS is close to 1 the signal is lost in the noise.

β-hydroxydecanoyl thiol ester dehydrase
2x171aa; P2₁2₁2₁; a=59.7Å, b=66.9Å, c=86.0 Å, R-axisII, 2x (9S)

resolution shell [Å]	traditional scaling					after corrections				
	R$_{merge}$ M	χ^2 M	R$_{merge}$ U	χ^2 U	AS	R$_{merge}$ M	χ^2 M	R$_{merge}$ U	χ^2 U	AS
20.0-4.33	0.014	3.75	0.017	2.71	1.38	0.010	2.57	0.006	0.97	2.65
4.33-3.44	0.019	4.20	0.020	4.42	0.95	0.009	1.60	0.006	0.94	1.71
3.44-3.01	0.024	3.26	0.025	3.74	0.87	0.012	1.47	0.009	1.05	1.39
3.01-2.73	0.028	2.57	0.030	2.88	0.89	0.017	1.36	0.013	0.98	1.39
overall	0.023	1.98	0.027	1.98	-	0.017	1.392	0.012	1.03	-

Scaling corrections - "typical" example

χ^2 M – merged Friedel pairs, U – unmerged Friedel pairs, AS – statistical significance of anomalous signal defined as a ratio χ^2 M to χ^2 U. When the value AS is close to 1 the signal is lost in the noise.

chymotrypsin
236 aa in ASU; P4₂2₁2; a=b=69.9 Å c=97.1 Å, R-axisII, 5 (S-S) and 2 S

resolution shell [Å]	traditional scaling					after corrections				
	R$_{merge}$ M	χ^2 M	R$_{merge}$ U	χ^2 U	AS	R$_{merge}$ M	χ^2 M	R$_{merge}$ U	χ^2 U	AS
40.0-4.07	0.075	26.2	0.074	28.3	0.93	0.015	2.30	0.012	1.57	1.47
4.07-3.23	0.096	35.4	0.095	39.6	0.89	0.016	1.78	0.013	1.54	1.16
3.23-2.82	0.110	31.1	0.108	35.0	0.89	0.019	1.58	0.017	1.39	1.14
2.82-2.56	0.121	27.9	0.119	31.4	0.89	0.022	1.42	0.019	1.23	1.15
overall	0.109	19.6	0.107	22.2	-	0.023	1.35	0.027	1.19	-

Merging of symmetry-related reflections

Symmetries:
- **crystal group symmetry (including identity)**
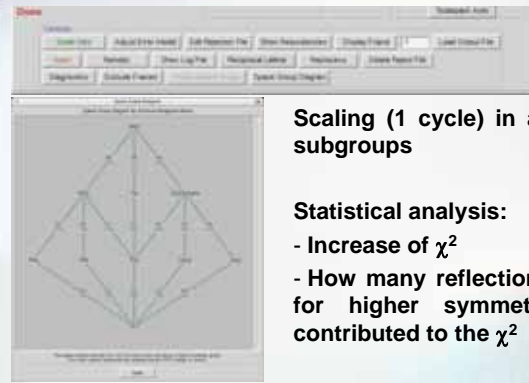- **Friedel symmetry**
- pseudosymmetry
    * inexact rotational crystal symmetry (phase transition)
- merohedral twinning, exact and inexact
- crystal (ir)reproducibility
- (in)variance during exposure

Merging - analysis

1. Determination of point group symmetry
- metric pseudosymmetries and relative indexing of different crystals
2. Parameters of error model (error scale factor, error systematic, rejection probability)
3. Assessment of data quality
- random events (signal-to-noise ratio)
- non-random events (outliers, ice-rings, bad frames etc.)
- non-isomorphism (radiation damage, pseudosymmetry)
4. Assessment of data content (significance of anomalous signal, systematic absences, translational pseudosymmetry - pseudosystematic absences)

Symmetry determination

Scaling (1 cycle) in all subgroups

Statistical analysis:

- **Increase of χ^2**
- **How many reflections for higher symmetry contributed to the χ^2**

Data collection – where to look?

- $I/\sigma(I)$
- R-merge
- χ^2 statistic
- Error model
- Detector area
- Phasing signal

$I/\sigma(I)$, R-merge, % of reflections measured with $I/\sigma(I) > 3$

$I/\sigma(I)$ is weighted statistics

- 2 quite reasonable limit

R-merge is unweighted statistics

- make no sense to calculate it for whole data set
- in resolution shells it gives valuable information, particularly at low resolution

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χ^2 statistics

Squared ratio of differences between equivalent measurements divided by expected errors

$$\frac{\left(I_{hkl}^{1} - \left\langle I_{hkl} \right\rangle \right)^{2}}{\sigma_{I_{hkl}}^{2} + \sigma_{\left\langle I_{hkl} \right\rangle}^{2}}$$

Expected value is around 1 for reasonable model of errors, however some departures are acceptable

0.9	-	5% overestimated errors
1.05	-	2.5% underestimated errors
1.1	-	5% underestimated errors
1.5	-	22% underestimated errors
2.0	-	40% underestimated errors

Error model

Based on the χ^2 test we can change the error model:
In HKL2000:
- error model (default value = 0.03)
  - change in resolution shells – be careful
  - if you have to go over 0.10 – something bad happened in experiment
- scale factor
  - more impact at higher resolution
  - default value 1.3
  - if you have to go over 2.0:
    - increase error density value in Denzo
    - non-isomorphism – accept χ^2

Non-optimal error model can kill phasing
The problem of error estimates – consequences of non-optimality of error estimates grow as a square of this non-optimality.
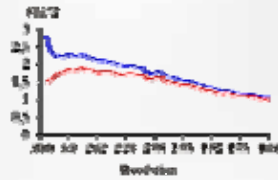
Do we have anomalous signal?

Comparison between two groups of reflections:

- equivalent reflections assuming no anomalous signal – Bijvoet pairs scaled together

- equivalent reflections assuming anomalous signal – Bijvoet pairs scaled separately

If anomalous signal present we should see significant discrepancy for Bijvoet pairs scaled together.

χ^2 = 2.0 (for together) vs. 1.0 (separately) ----- 40% of difference – large not small

The significance of this difference is multiplied by redundancy factor

$$\frac{\chi^2_{all\ together}}{\chi^2_{separate}} \cdot redundancy \geq 2$$

Beam stop

Always remove beam stop shadow!!!

What happens if you do not remove:

Reflections measured correctly will be averaged with equivalent reflections in the beam-stop region (very low or no intensity)

Rejecting outliers will not always work correctly